

CS 188: Artificial Intelligence

Spring 2010

Lecture 8: MEU / Utilities
2/11/2010

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Many slides over the course adapted from Dan Klein

Announcements

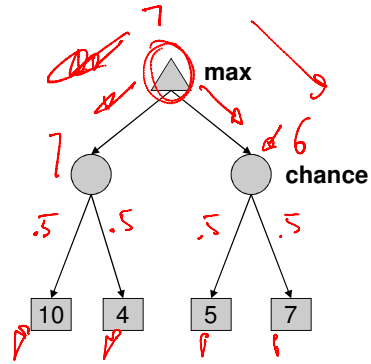
- W2 is due today (lecture or drop box)
- P2 is out and due on 2/18

Expectimax Search Trees

- What if we don't know what the result of an action will be? E.g.,
 - In solitaire, next card is unknown
 - In minesweeper, mine locations
 - In pacman, the ghosts act randomly

- Can do **expectimax search**
 - Chance nodes, like min nodes, except the outcome is uncertain
 - Calculate **expected utilities**
 - Max nodes as in minimax search
 - Chance nodes take average (expectation) of value of children

- Later, we'll learn how to formalize the underlying problem as a **Markov Decision Process**



4

Maximum Expected Utility

- Why should we average utilities? Why not minimax?
- Principle of maximum expected utility: an agent should choose the action which **maximizes its expected utility, given its knowledge**
- General principle for decision making
- Often taken as the definition of rationality
- We'll see this idea over and over in this course!
- Let's decompress this definition...
 - Probability --- Expectation --- Utility

5

Reminder: Probabilities

- A **random variable** represents an event whose outcome is unknown
- A **probability distribution** is an assignment of weights to outcomes
- Example: traffic on freeway?
 - Random variable: T = amount of traffic
 - Outcomes: T in {none, light, heavy}
 - Distribution: $P(T=\text{none}) = 0.25$, $P(T=\text{light}) = 0.55$, $P(T=\text{heavy}) = 0.20$
- Some laws of probability (more later):
 - Probabilities are always non-negative
 - Probabilities over all possible outcomes sum to one
- As we get more evidence, probabilities may change:
 - $P(T=\text{heavy}) = 0.20$, $P(T=\text{heavy} \mid \text{Hour}=8\text{am}) = 0.60$
 - We'll talk about methods for reasoning and updating probabilities later

6

What are Probabilities?

- Objectivist / frequentist answer:
 - Averages over repeated *experiments*
 - E.g. empirically estimating $P(\text{rain})$ from historical observation
 - Assertion about how future experiments will go (in the limit)
 - New evidence changes the *reference class*
 - Makes one think of *inherently random* events, like rolling dice
- Subjectivist / Bayesian answer:
 - Degrees of belief about unobserved variables
 - E.g. an agent's belief that it's raining, given the temperature
 - E.g. pacman's belief that the ghost will turn left, given the state
 - Often *learn* probabilities from past experiences (more later)
 - New evidence *updates beliefs* (more later)

7

Uncertainty Everywhere

- Not just for games of chance!
 - I'm sick: will I sneeze this minute?
 - Email contains "FREE!": is it spam? ←
 - Tooth hurts: have cavity? ←
 - 60 min enough to get to the airport?
 - Robot rotated wheel three times, how far did it advance?
 - Safe to cross street? (Look both ways!)

- Sources of uncertainty in random variables:
 - ▪ Inherently random process (dice, etc)
 - ▪ Insufficient or weak evidence
 - ▪ Ignorance of underlying processes
 - ▪ Unmodeled variables
 - The world's just noisy – it doesn't behave according to plan!

9

Reminder: Expectations

- We can define function $f(X)$ of a random variable X
- The expected value of a function is its average value, weighted by the probability distribution over inputs
- Example: How long to get to the airport?
 - Length of driving time as a function of traffic: $L(T)$
 $L(\text{none}) = 20, L(\text{light}) = 30, L(\text{heavy}) = 60$
 - What is my expected driving time?
 - Notation: $E[L(T)]$
 - Remember, $P(T) = \{\text{none: } 0.25, \text{light: } 0.5, \text{heavy: } 0.25\}$
 - $E[L(T)] = L(\text{none}) * P(\text{none}) + L(\text{light}) * P(\text{light}) + L(\text{heavy}) * P(\text{heavy})$
 - $E[L(T)] = (20 * 0.25) + (30 * 0.5) + (60 * 0.25) = 35$

10

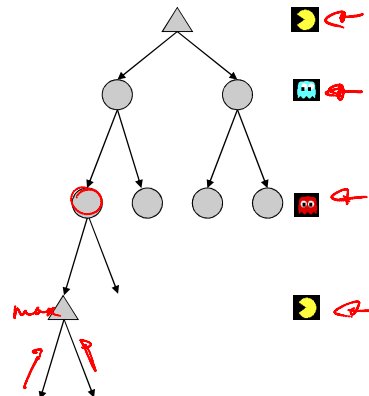
Utilities

- Utilities are functions from outcomes (states of the world) to real numbers that describe an agent's preferences
- Where do utilities come from?
 - In a game, may be simple (+1/-1)
 - Utilities summarize the agent's goals
 - Theorem: any set of preferences between outcomes can be summarized as a utility function (provided the preferences meet certain conditions)
- In general, we hard-wire utilities and let actions emerge (why don't we let agents decide their own utilities?)
- More on utilities soon...

12

Expectimax Search

- In expectimax search, we have a probabilistic model of how the opponent (or environment) will behave in any state
 - Model could be a simple uniform distribution (roll a die)
 - Model could be sophisticated and require a great deal of computation
 - We have a node for every outcome out of our control: opponent or environment
 - The model might say that adversarial actions are likely!
- For now, assume for any state we magically have a distribution to assign probabilities to opponent actions / environment outcomes

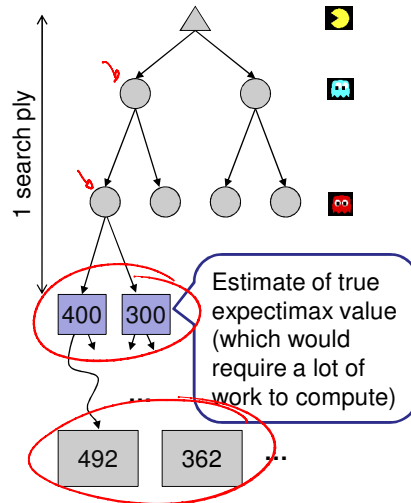


Having a probabilistic belief about an agent's action does not mean that agent is flipping any coins!

13

Expectimax Search

- Chance nodes
 - Chance nodes are like min nodes, except the outcome is uncertain
 - Calculate **expected utilities**
 - Chance nodes average successor values (weighted)
- Each chance node has a **probability distribution** over its outcomes (called a **model**)
 - For now, assume we're given the model
- Utilities for terminal states
 - Static evaluation functions give us limited-depth search

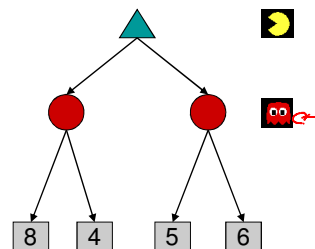


Expectimax Pseudocode

```
def value(s)
  if s is a max node return maxValue(s)
  if s is an exp node return expValue(s)
  if s is a terminal node return evaluation(s)
```

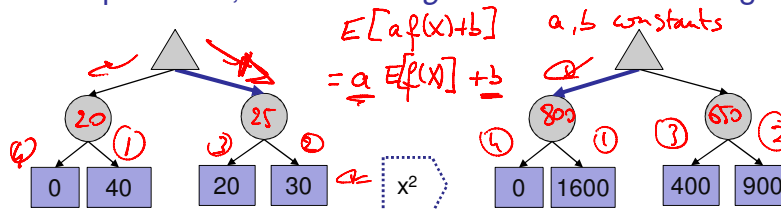
```
def maxValue(s)
  values = [value(s') for s' in successors(s)]
  return max(values)
```

```
def expValue(s)
  values = [value(s') for s' in successors(s)]
  weights = [probability(s, s') for s' in successors(s)]
  return expectation(values, weights)
```



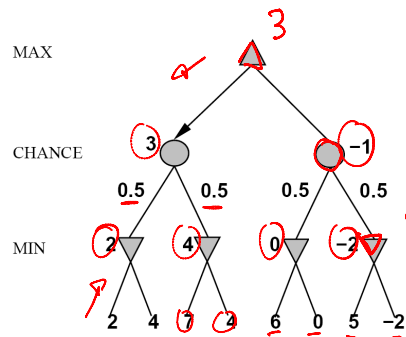
Expectimax Evaluation

- Evaluation functions quickly return an estimate for a node's true value (which value, expectimax or minimax?)
- For minimax, evaluation function scale doesn't matter
 - We just want better states to have higher evaluations (get the ordering right)
 - We call this **insensitivity to monotonic transformations**
- For expectimax, we need *magnitudes* to be meaningful



Mixed Layer Types

- E.g. Backgammon
- Expectiminimax
 - Environment is an extra player that moves after each agent
 - Chance nodes take expectations, otherwise like minimax

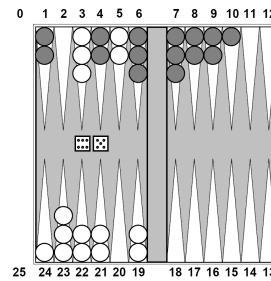


ExpectiMinimax-Value(*state*):

- if *state* is a MAX node then
 - return the highest EXPECTIMINIMAX-VALUE of SUCCESSORS(*state*)
- if *state* is a MIN node then
 - return the lowest EXPECTIMINIMAX-VALUE of SUCCESSORS(*state*)
- if *state* is a chance node then
 - return average of EXPECTIMINIMAX-VALUE of SUCCESSORS(*state*)

Stochastic Two-Player

- Dice rolls increase b : 21 possible rolls with 2 dice
 - Backgammon ≈ 20 legal moves
 - Depth 4 = $20 \times (21 \times 20)^3 = 1.2 \times 10^9$
- As depth increases, probability of reaching a given node shrinks
 - So value of lookahead is diminished
 - So limiting depth is less damaging
 - But pruning is less possible...
- TDGammon uses depth-2 search + very good eval function + reinforcement learning: world-champion level play



23

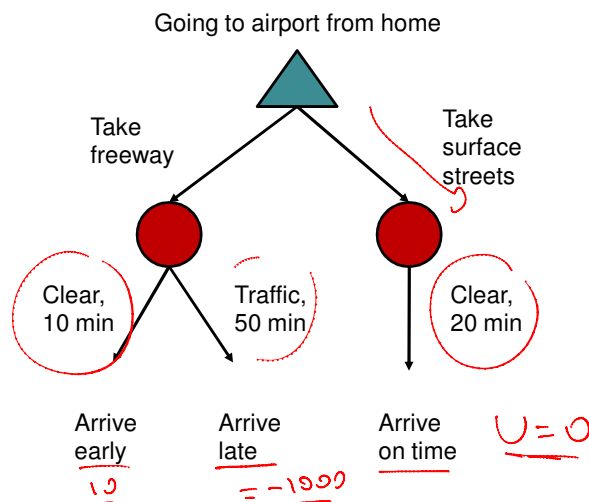
24

Maximum Expected Utility

- Principle of maximum expected utility:
 - A rational agent should choose the action which **maximizes its expected utility, given its knowledge**
- Questions:
 - ▪ Where do utilities come from?
 - ▪ How do we know such utilities even exist?
 - ▪ Why are we taking expectations of utilities (not, e.g. minimax)?
 - ▪ What if our behavior can't be described by utilities?

25

Utilities: Unknown Outcomes



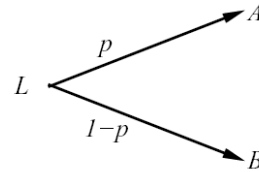
26

Preferences

- An agent chooses among:

- Prizes: A, B , etc.
- Lotteries: situations with uncertain prizes

$$\rightarrow L = [p, A; (1-p), B]$$



- Notation:

- $\rightarrow A \succ B$ A preferred over B
- $\rightarrow A \sim B$ indifference between A and B
- $\rightarrow A \succeq B$ B not preferred over A

27

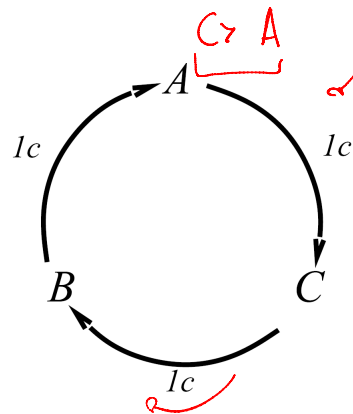
Rational Preferences

- We want some constraints on preferences before we call them rational

$$(A \succ B) \wedge (B \succ C) \Rightarrow (A \succ C)$$

- For example: an agent with **intransitive preferences** can be induced to give away all of its money

- If $B \succ C$, then an agent with C would pay (say) 1 cent to get B
- If $A \succ B$, then an agent with B would pay (say) 1 cent to get A
- If $C \succ A$, then an agent with A would pay (say) 1 cent to get C



28

Rational Preferences

- Preferences of a rational agent must obey constraints.

- The **axioms of rationality**:

→ Orderability

$$(A \succ B) \vee (B \succ A) \vee (A \sim B)$$

→ Transitivity

$$(A \succ B) \wedge (B \succ C) \Rightarrow (A \succ C)$$

→ Continuity

$$A \succ B \succ C \Rightarrow \exists p [p, A; 1-p, C] \sim B$$

Substitutability

$$A \sim B \Rightarrow [p, A; 1-p, C] \sim [p, B; 1-p, C]$$

Monotonicity

$$A \succ B \Rightarrow$$

$$(p \geq q) \Rightarrow [p, A; 1-p, B] \succeq [q, A; 1-q, B]$$

- Theorem: Rational preferences imply behavior describable as maximization of expected utility**

29

MEU Principle

- Theorem:**

- [Ramsey, 1931; von Neumann & Morgenstern, 1944]
- Given any preferences satisfying these constraints, there exists a real-valued function U such that:

$$U(A) \geq U(B) \Leftrightarrow A \succeq B$$

$$\rightarrow U([p_1, S_1; \dots; p_n, S_n]) = \sum_i p_i U(S_i)$$

- Maximum expected utility (MEU) principle:**

- Choose the action that maximizes expected utility
- Note:** an agent can be entirely rational (consistent with MEU) without ever representing or manipulating utilities and probabilities
- E.g., a lookup table for perfect tictactoe

30

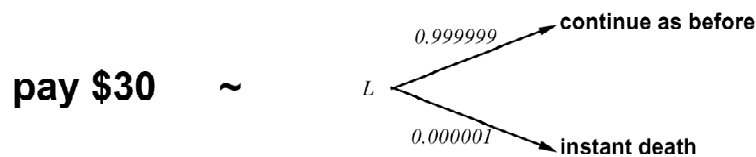
Utility Scales

- Normalized utilities: $u_+ = 1.0, u_- = 0.0$
 - Micromorts: one-millionth chance of death, useful for paying to reduce product risks, etc.
 - QALYs: quality-adjusted life years, useful for medical decisions involving substantial risk
 - Note: behavior is invariant under positive linear transformation
- $\rightarrow U'(x) = k_1 U(x) + k_2$ where $k_1 > 0$
- With deterministic prizes only (no lottery choices), only ordinal utility can be determined, i.e., total order on prizes

31

Human Utilities

- Utilities map states to real numbers. Which numbers?
 - Standard approach to assessment of human utilities:
 - Compare a state A to a standard lottery L_p between
 - "best possible prize" u_+ with probability p
 - "worst possible catastrophe" u_- with probability $1-p$
 - Adjust lottery probability p until $A \sim L_p$
- \rightarrow Resulting p is a utility in $[0,1]$

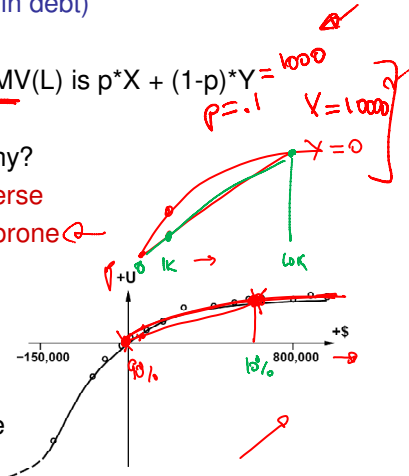


32

Money

$$U([p, A], (1-p), B) = pU(A) + (1-p)U(B)$$

- Money does not behave as a utility function, but we can talk about the utility of having money (or being in debt)
- Given a lottery $L = [p, \$X; (1-p), \$Y]$
 - The **expected monetary value** $EMV(L)$ is $p \cdot X + (1-p) \cdot Y = 1000$
 - $U(L) = p \cdot U(\$X) + (1-p) \cdot U(\$Y)$
 - Typically, $U(L) < U(EMV(L))$: why?
 - In this sense, people are **risk-averse**
 - When deep in debt, we are **risk-prone**
- Utility curve: for what probability p am I indifferent between:
 - Some sure outcome x
 - A lottery $[p, \$M; (1-p), \$0]$, M large



33

Example: Insurance

- Consider the lottery $[0.5, \$1000; 0.5, \$0]$
 - What is its **expected monetary value**? (\$500)
 - What is its **certainty equivalent**?
 - Monetary value acceptable in lieu of lottery
 - \$400 for most people
 - Difference of \$100 is the **insurance premium**
 - There's an insurance industry because people will pay to reduce their risk
 - If everyone were risk-neutral, no insurance needed!

35

Example: Insurance

- Because people ascribe different utilities to different amounts of money, insurance agreements can increase both parties' expected utility

You own a car. Your lottery:

$L_Y = [0.8, \$0 ; 0.2, -\$200]$

i.e., 20% chance of crashing

You do not want $-\$200!$

$$U_Y(L_Y) = 0.2 * U_Y(-\$200) = -200$$

$$U_Y(-\$50) = -150$$

Amount	Your Utility U_Y
\$0	0
-\$50	-150
-\$200	-1000

Example: Insurance

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$$U_Y(-\$50) = -150$$

Insurance company buys risk:

$L_I = [0.8, \$50 ; 0.2, -\$150]$

i.e., \$50 revenue + your L_Y

Insurer is risk-neutral:

$$U(L) = U(\text{EMV}(L))$$

$$\begin{aligned} U_I(L_I) &= U(0.8 * 50 + 0.2 * (-150)) \\ &= U(\$10) > U(\$0) \end{aligned}$$

Example: Human Rationality?

- Famous example of Allais (1953)
 - A: [0.8,\$4k; 0.2,\$0]
 - B: [1.0,\$3k; 0.0,\$0]
 - C: [0.2,\$4k; 0.8,\$0]
 - D: [0.25,\$3k; 0.75,\$0]
- Most people prefer $B > A$, $C > D$
- But if $U(\$0) = 0$, then
 - $B > A \Rightarrow U(\$3k) > 0.8 U(\$4k)$
 - $C > D \Rightarrow 0.8 U(\$4k) > U(\$3k)$

38

39